EAST Search History

Ref#	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	5597	((396/5,419,428,429) or (348/373,375,552)). OQLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/20 17:59
S2	14822	St and (tripod near2 (head or stand or pedestal or support)) or (camera near2 (stand or pedestal or tripod or support))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/20 18:14
S3	1239	S1 and ((tripod near2 (head or stand or pedestal or support)) or (camera near2 (stand or pedestal or tripod or support)))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/20 18:14
S4	56	S3 and (counter adj2 (weight or balance or balancing))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/20 18:15
\$5	18	S3 and ((restore or restoring) near2 (force or torque or moment))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/20 18:24
S6	85	St and (sinusoid or sinusoidal or sine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/20 18:28
S7	18	S3 and (sinusoid or sinusoidal or sine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/20 18:28
S8	0	("2004/0016857").URPN.	USPAT	AND	ON	2009/05/20 18:34
S9	1	(10/362617). APP .	USPAT; USOCR	AND	ON	2009/05/20 18:34
S10	6	("2684822" "3804356" "4621785" "5379991" "63545444").PN. OR ("6857794").URPN.	US-PGPUB; USPAT; USOCR	AND	ON	2009/05/20 18:34

S11	5762	((396.5,419,428,429) or (348/373,375) or (248/177.1,597,372.1,292.11-292.13,123.11)) COLS	US-PGPUB; USPAT; USOCR, FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/21 10:20
S13	1332	S11 and ((tripod near2 (head or stand or pedestal or support)) or (camera near2 (stand or pedestal or tripod or support)))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:22
S14	6009	((396/5,419,428,429) or (348/373,375) or (248/177.1,597,372.1,292.11-292.13,123.11,183.3,183.4)).OQLS	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/05/21 10:24
S15	1395	\$14 and ((tripod near2 (head or stand or pedestal or support)) or (camera near2 (stand or pedestal or tripod or support)))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:24
S16	1032	S14 and (tripod or pedestal)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:25
S17	18	S15 and (roll with gear)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:25
S18	9	S15 and (roll with gear) NOT crane	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:25
S19	1314	S15 not crane	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:48
\$21	25	S19 and ((restore or restoring) near2 (force or torque or moment))	US-PGPUB; USPAT; USOCR, FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:49

S22	1171	\$19 and (@ad<="20041020" or @pd<="20041020" or @ilad<="20041020" or @ripd<="20041020")	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:58
S23	19	S22 and ((frestore or restoring) near2 (force or torque or moment))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 10:58
S24	17	("1862755" "3223376" "3385550" "3845928" "4447033" "4466590" "4673268").PN. OR ("4771979").URPN.	US-PGPUB; USPAT; USOCR	AND	ON	2009/05/21 13:22
S25	15	\$22 and (sinusoid or sinusoidal or sine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 13:38
S26	15	S25 not crane	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 13:38
S27	5451	\$14 and (@ad<="20041020" or @pd<="20041020" or @rlad<="20041020" or @rlpd<="20041020")	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:15
S28	74	\$27 and (sinusoid or sinusoidal or sine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:16
S29	51	\$28 not (\$25 or crane)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:16
S30	1066	\$27 and (roller or cam)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:44
\$31	164	\$27 and ((roller or cam) with force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:44

S32	191	\$27 and ((roller or cam) with (force or torque or moment))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:44
S33	15	\$32 and (sinusoid or sinusoidal or sine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:45
S34	34	\$32 and (sinusoid or sinusoidal or sine or sin")	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:45
\$35	21	\$32 and ("sin")	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:45
S36	26	S34 not crane	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 14:45
\$37	883	(sinusoid or sinusoidal or sine or "sin") and ((tripod near2 (head or stand or pedestal or support)) or (camera near2 (stand or pedestal or tripod or support)))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 15:26
S38	71	\$37 and ((roller or cam) with (force or torque or moment))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 15:27
S39	13	((sinusoid or sinusoidal or sine or "sin") same ((roller or cam) with (force or torque or moment))) and ((tripod near2 (head or stand or pedestal or support)) or (camera near2 (stand or pedestal or tripod or support)))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/21 15:27

S40	50	(US 20040206863.\$ or US 20070172228-\$ or US 20050220576-\$ or US 20050220576-\$ or US 20060176485.\$ or US 20060176485.\$ or US 20060176495.\$ or US 200602062-\$ or US 2006023219-\$ or US 2006023219-\$ or US 2006023219-\$ or US 2006023219-\$ or US 20060032319-\$ or US 20060032319-\$ or US 2006003219-\$ or US 55990247-\$ or US 4906045-\$ or US 5990247-\$ or US 4906045-\$ or US 5026091-\$ or US 4907461-\$ or US 5026091-\$ or US 4907461-\$ or US 4057610-\$ or US 405761-\$ or US 4057610-\$ or US 40576	US-PGPUB; USPAT	AND	ON	2009/05/22
541	50	(US-20040206863-\$ or US-20070172228-\$ or US-2000607548-\$ or US-2000607548-\$ or US-2006007548-\$ or US-2006007548-\$ or US-2006007548-\$ or US-20060075480-\$ or US-20060023019-\$), did. or (US-555821-\$ or US-5905003219-\$), did. or (US-555821-\$ or US-59052075-\$ or US-4457610-\$ or US-59022075-\$ or US-4457610-\$ or US-4905451-\$ or US-502691-\$ or US-4906045-\$ or US-502691-\$ or US-4906045-\$ or US-502691-\$ or US-4907451-\$ or US-50560510-\$ or US-580510-\$ or US-5805079-\$ or US-4457613-\$ or US-590500500-\$ or US-5905079-\$ or US-590507-\$ or US-59	US-PGPUB; USPAT	AND	ŌN	2009/05/22
S42	51	S40 or S41	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/22 12:23
S43	6	("2845263").PN. OR ("5605101").URPN.	US-PGPUB; USPAT; USOCR	AND	ON	2009/05/22 12:26

S44	71	"310".clas. and (tripod)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 12:52
S45	6036	"310".clas. and (tripod near2 (head or stand or pedestal)) or (camera near2 (stand or pedestal or tripod))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 12:53
S46	4930	S45 and (@ad<="20041020" or @pd<="20041020" or @rlad<="20041020" or @rlpd<="20041020")	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 12:53
S47	108	\$46 and (sinusoid or sinusoidal or sine)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 12:53
S48	55	S47 and (roller or roll or cam)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 12:54
S49	3045	S46 and tripod	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 13:00
\$50	6	"310".clas. and ((tripod near2 (head or stand or pedestal)) or (camera near2 (stand or pedestal or tripod)))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23
S51	65	S44 and (@ad<="20041020" or @pd<="20041020" or @ilad<="20041020" or @ripd<="20041020")	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 13:01
S52	4	kistner-bernhard.in. or kistner-bernhard-\$. in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM TDB	AND	ON	2009/05/23 13:06

S53	28	(tripod moment rotation\$2 or rotat\$3 roll gear (sinusoid\$4 or sine or "sin")).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 13:08
S54	1	(tripod moment (rotation\$2 or rotat\$3) roll gear (sinusoid\$4 or sine or "sin")).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2009/05/23 13:11
S55	8	("4083524" "4570887" "4955568" "4959671" "4979709" "5222826").PN. OR ("5413295").URPN.	US-PGPUB; USPAT; USOCR	AND	ON	2009/05/23 13:13

^{5/23/2009 2:03:57} PM

C:\ Documents and Settings\ badams\ My Documents\ EAST\ Workspaces\ series 10\ 10-579371 Kistner.wsp